

Principles of Real-Time Programming

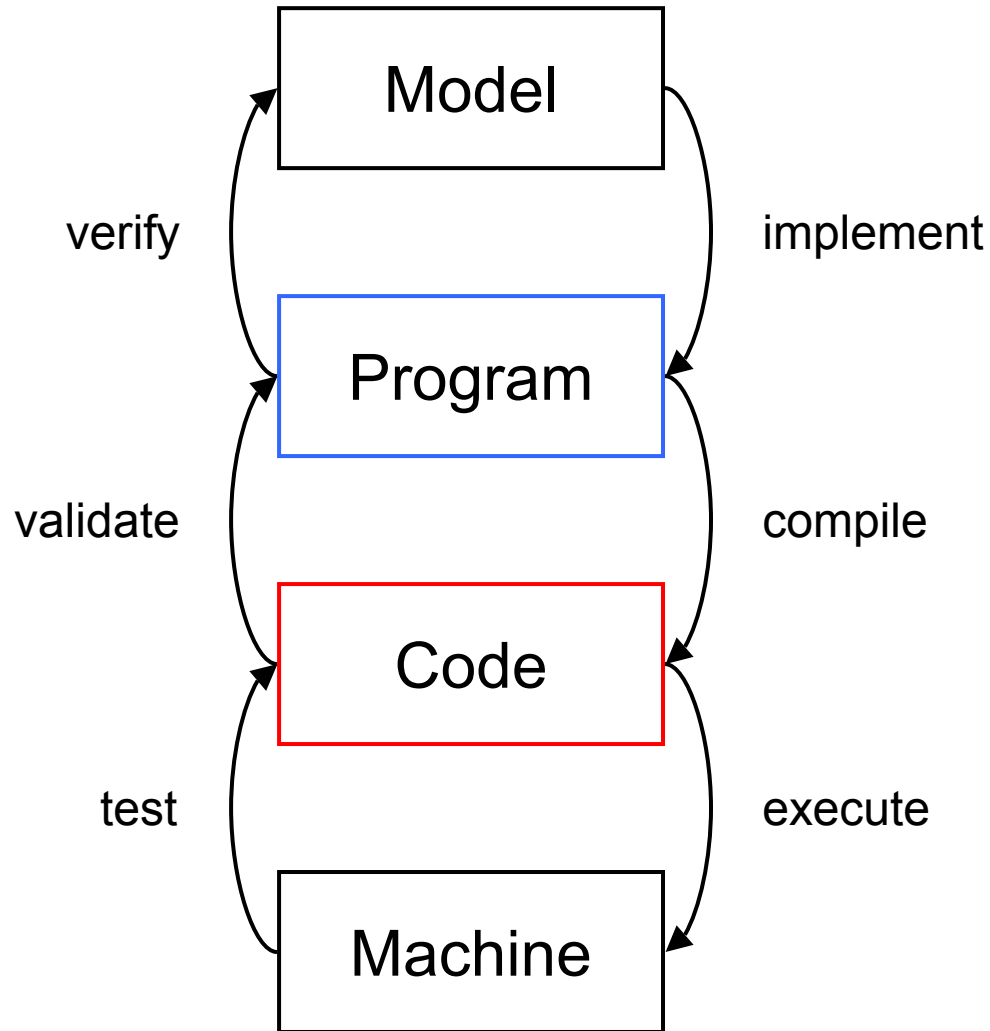
EMSOFT 2002

Christoph M. Kirsch

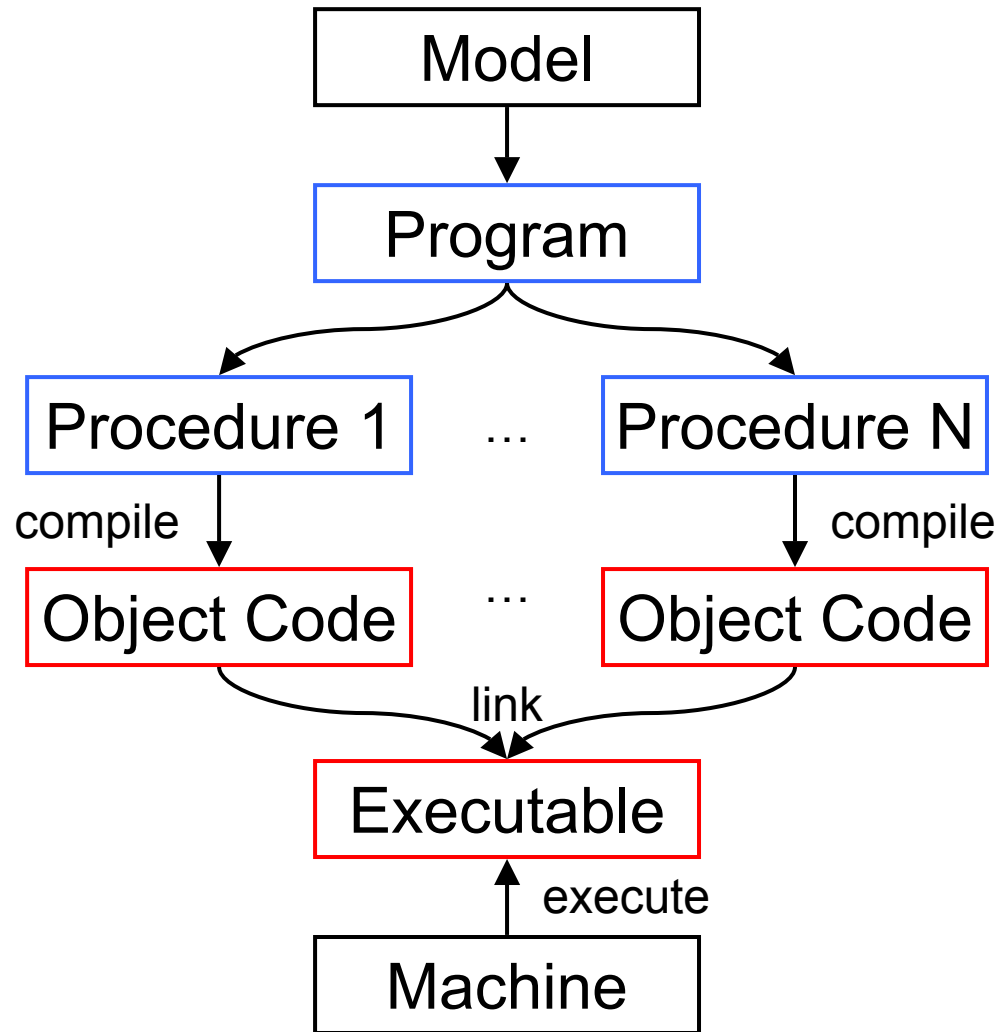
UC Berkeley

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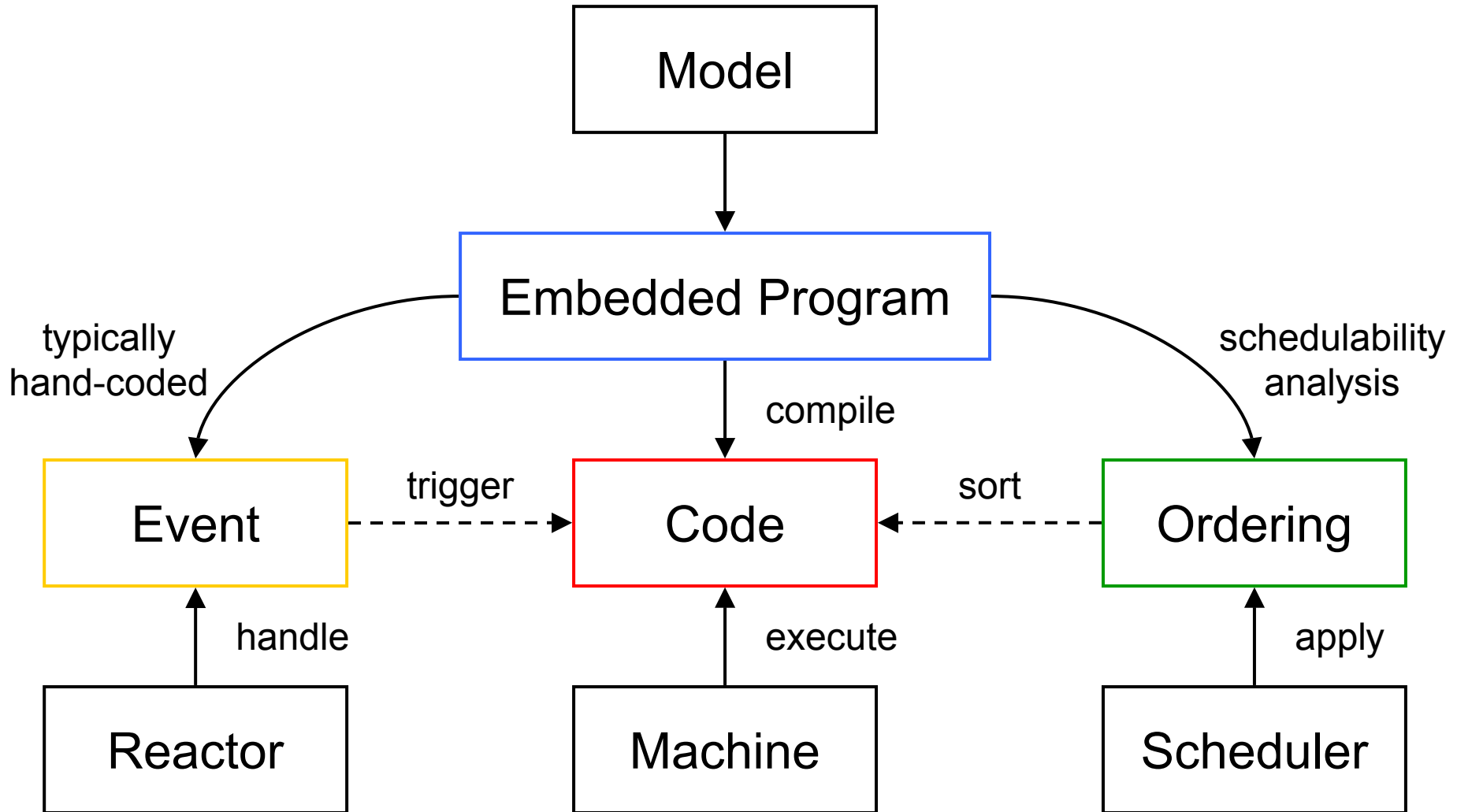
Sequential Programming



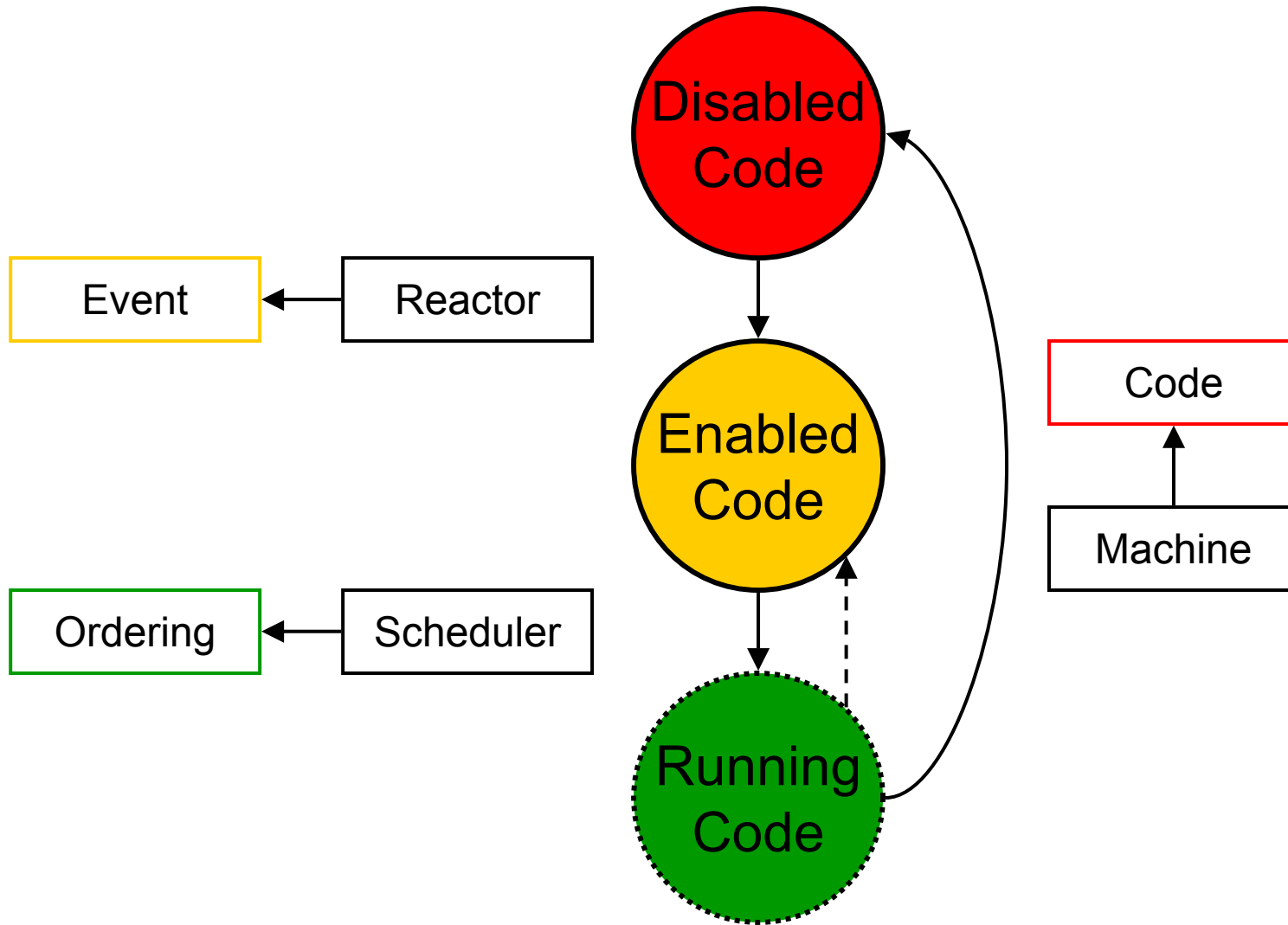
Composability and Type Safety



Embedded Programming

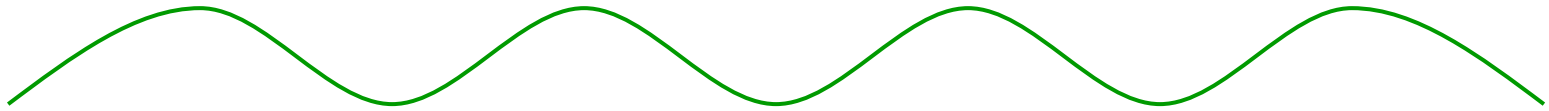


A Real-Time Process Model



Embedded Software

Environment



Environment Processes

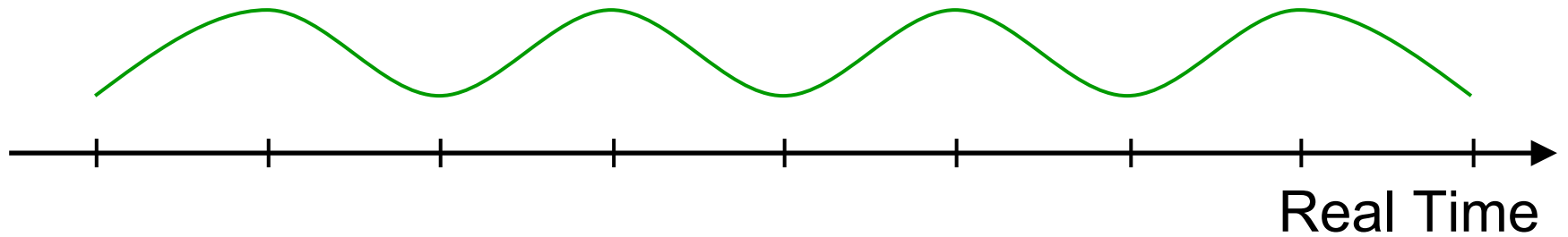
Software Processes



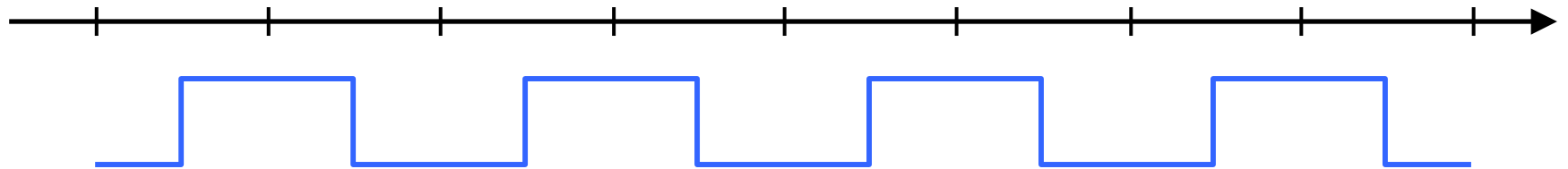
Software

Real Time vs. Soft Time

Environment

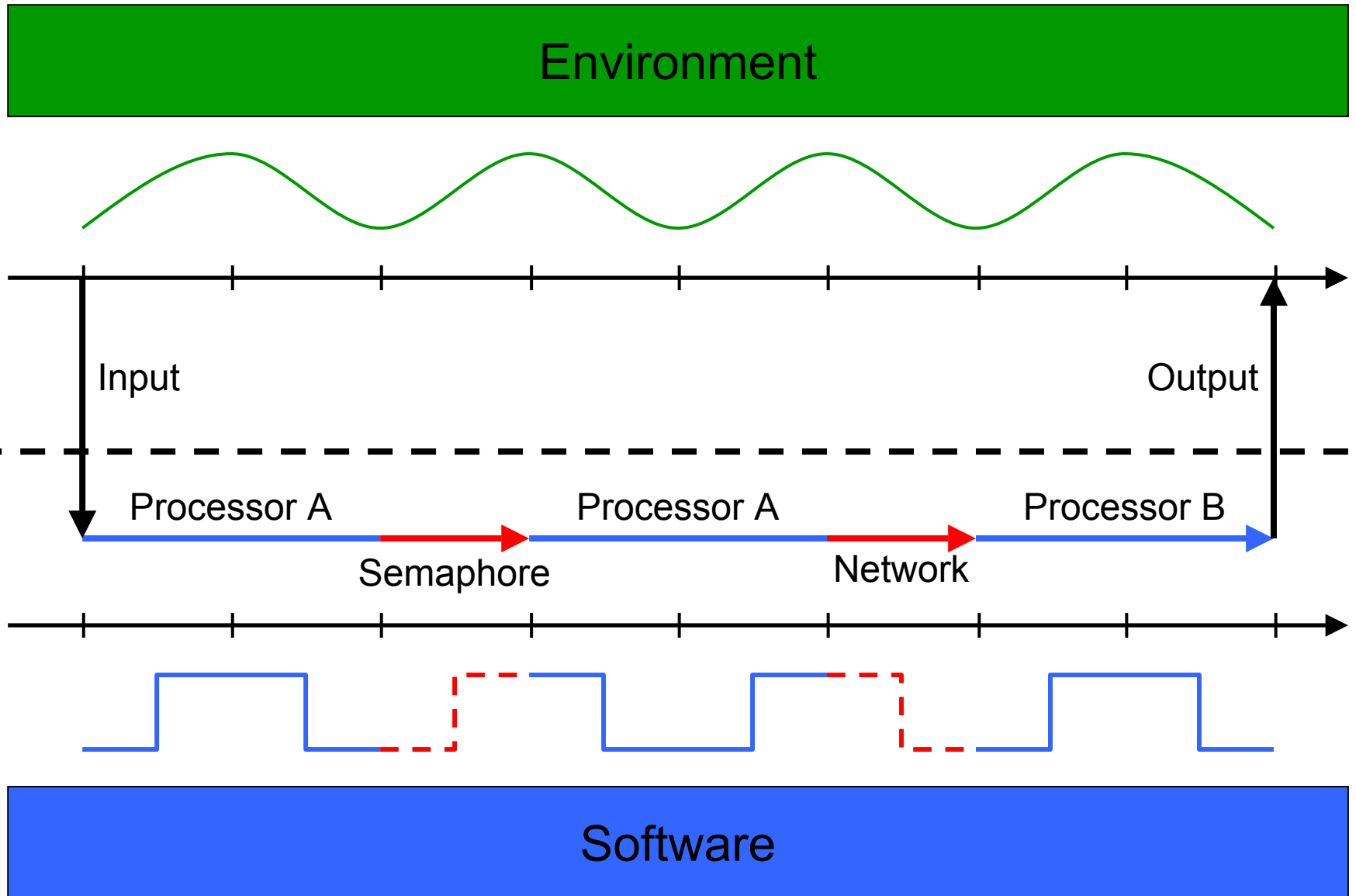


Soft Time

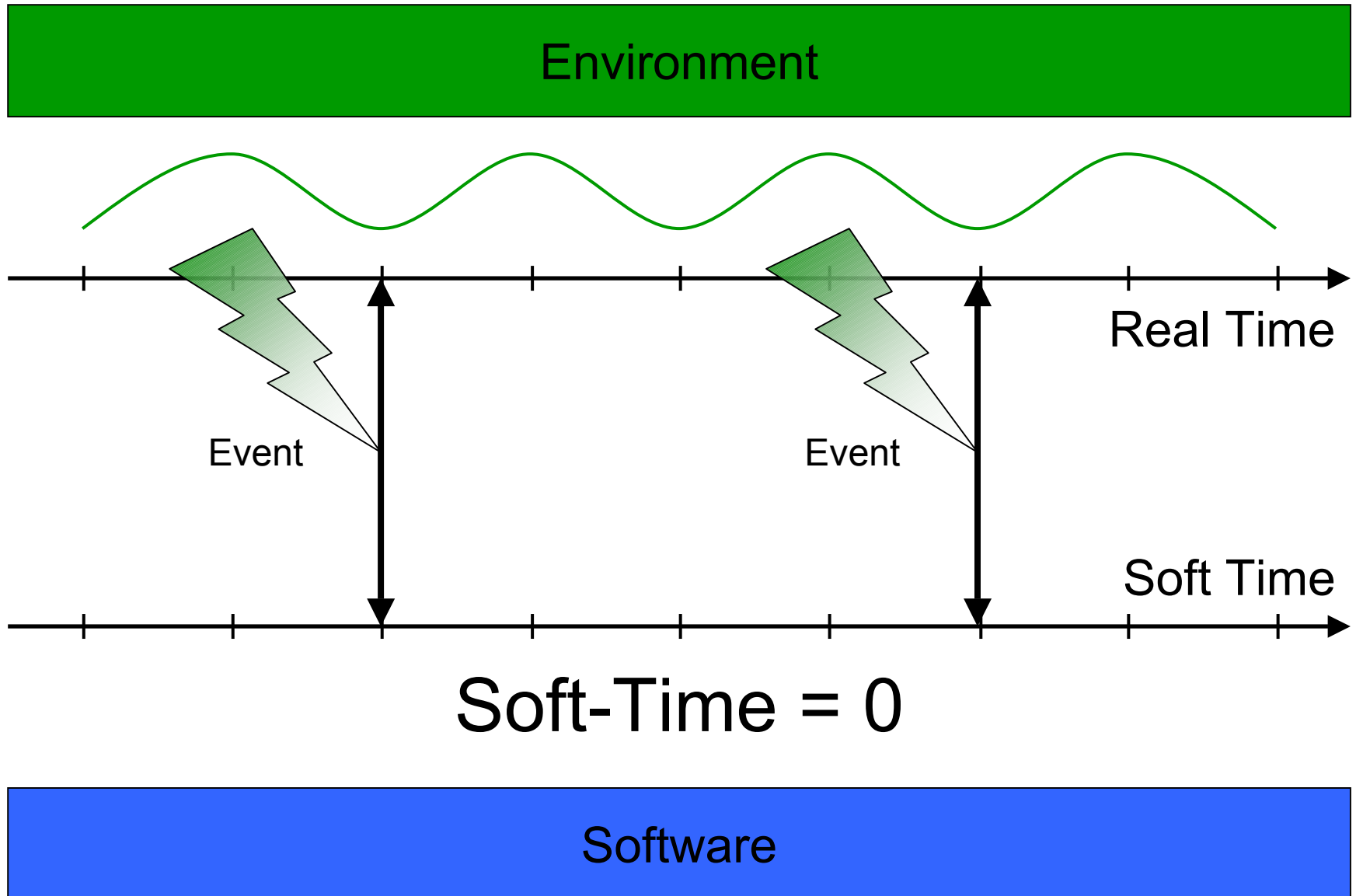


Software

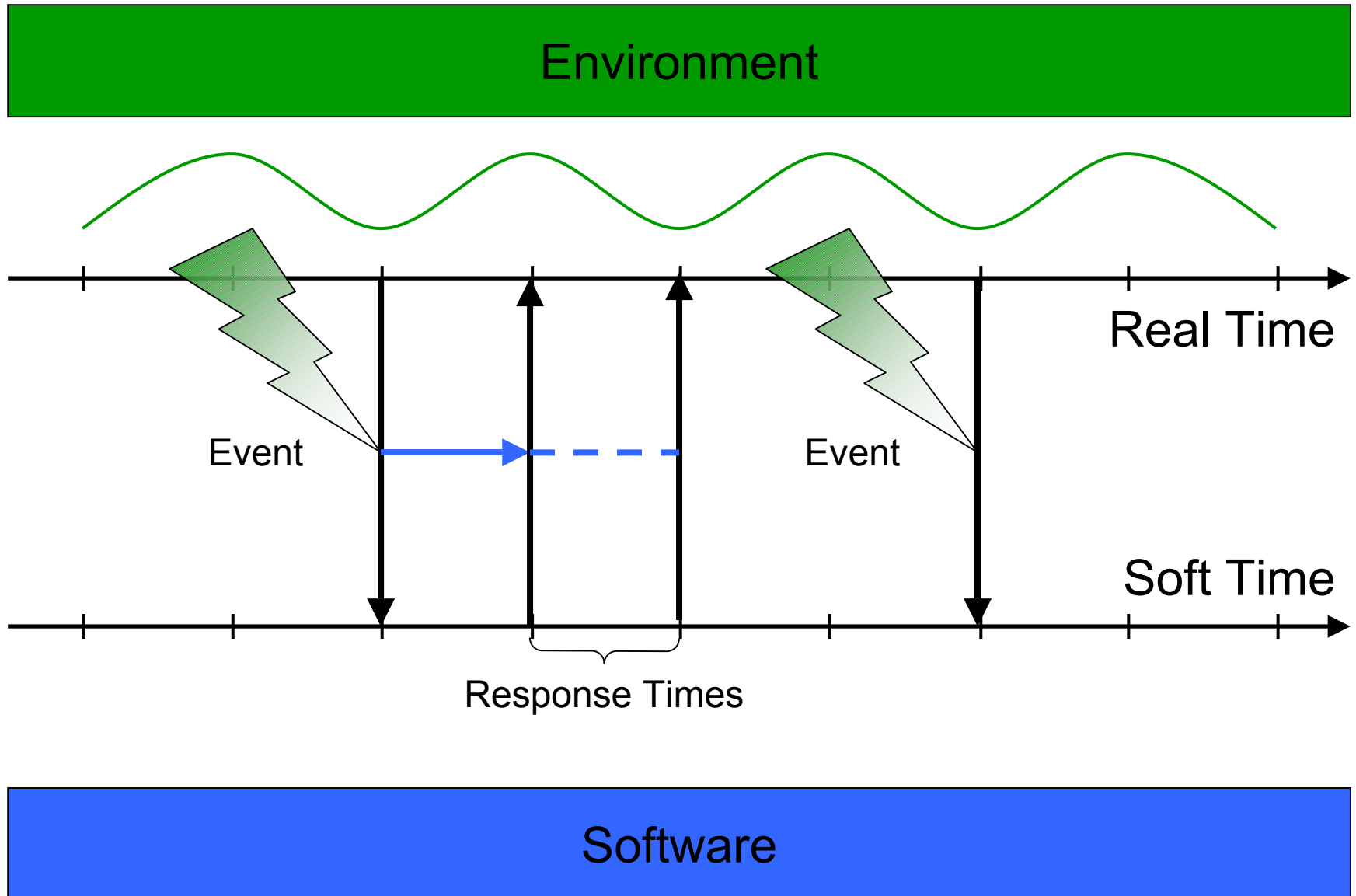
Soft Time



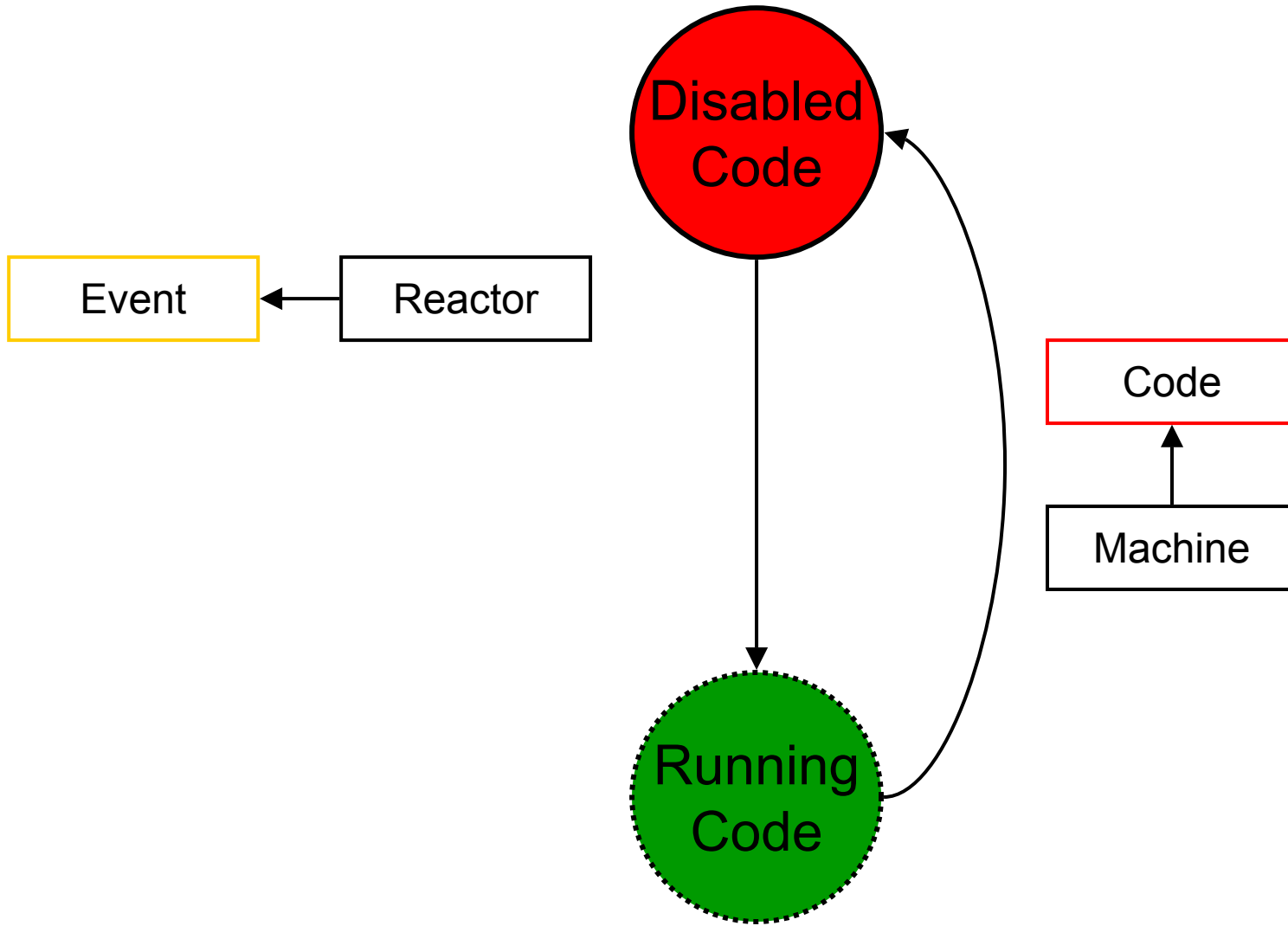
The Synchronous Model



A Synchronous Implementation



Event Safety



Synchrony

Environment

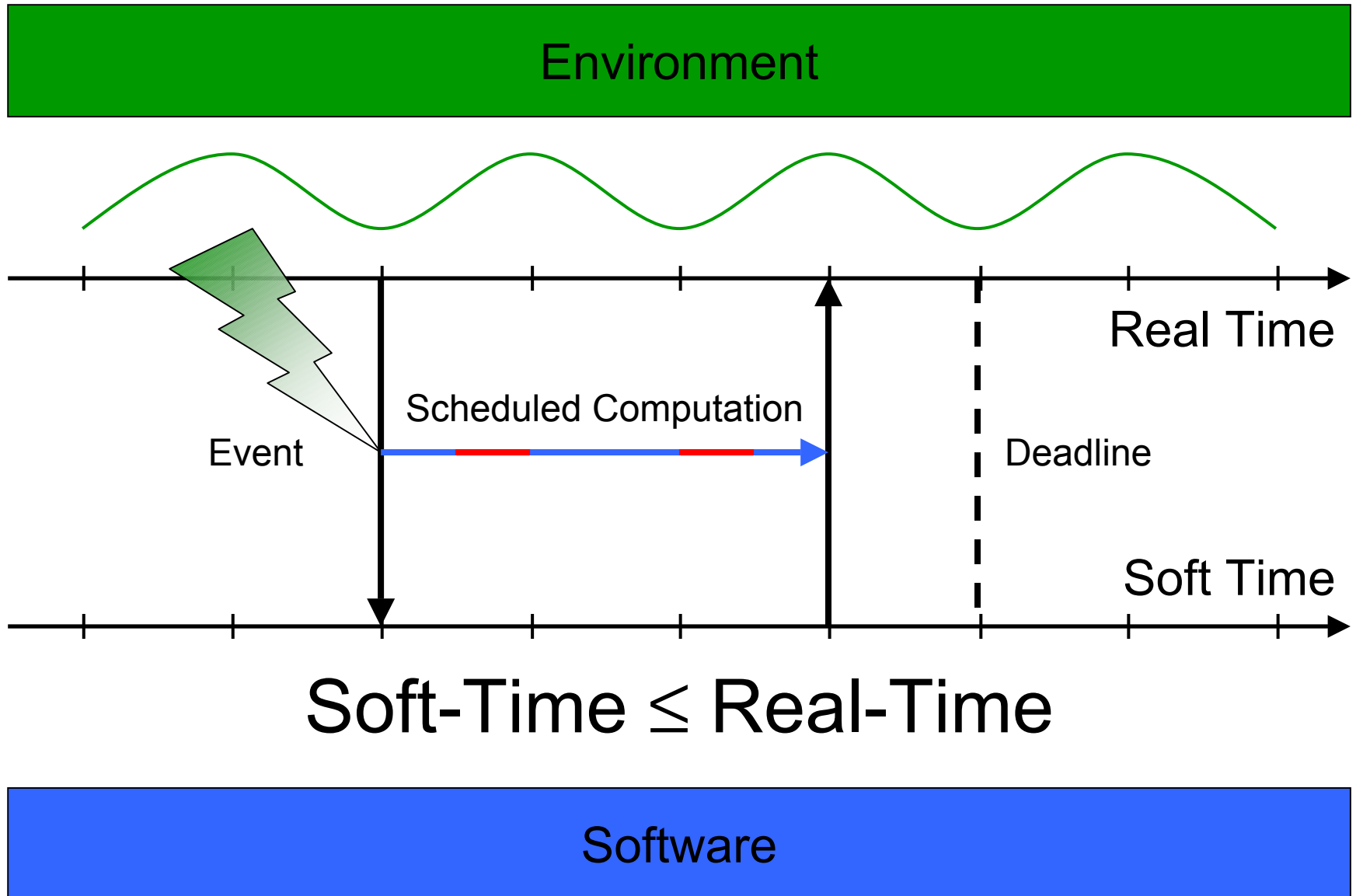
Real Time

Input

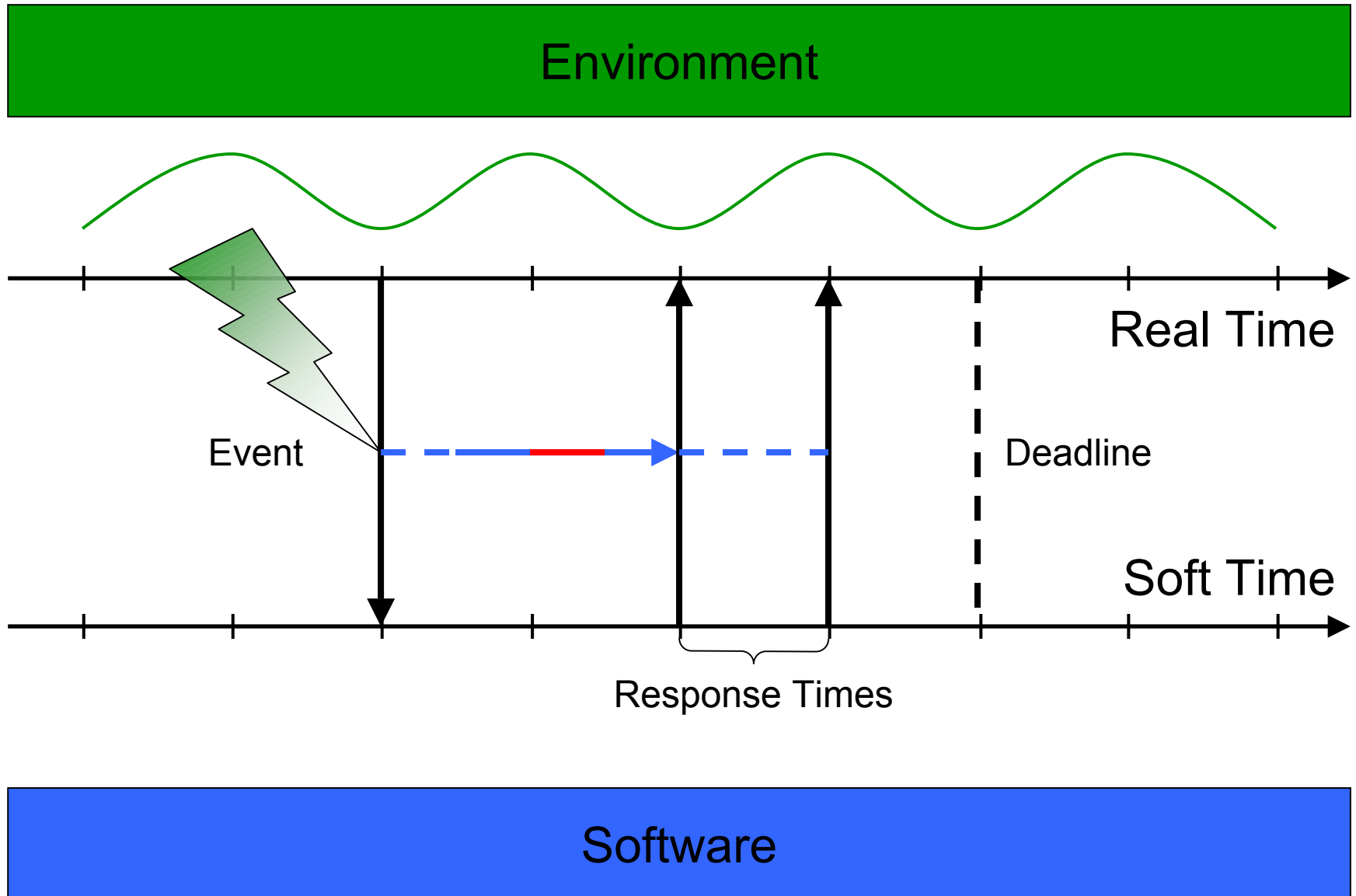
Output

Software

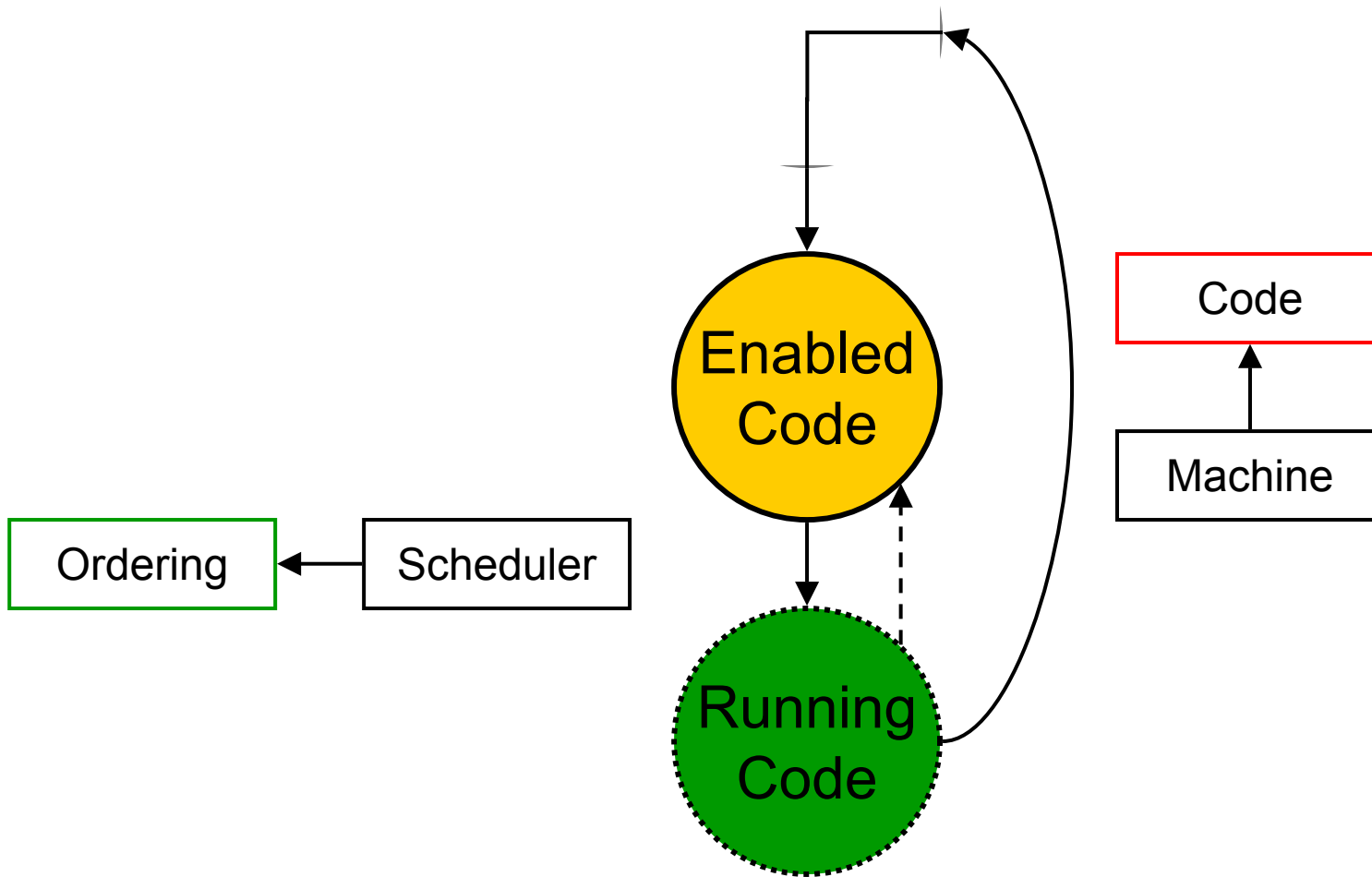
The Scheduled Model



A Scheduled Implementation

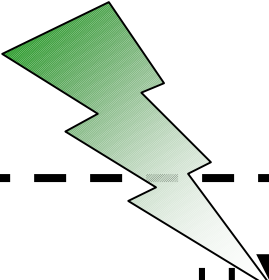
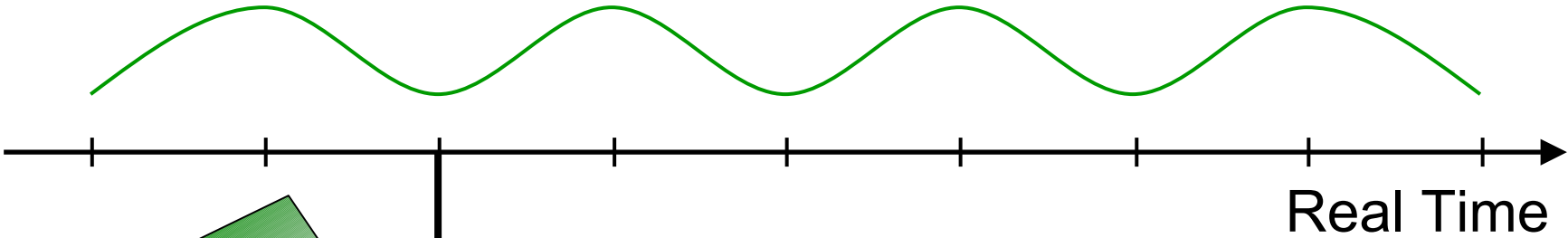


Space Safety



Priority Inversion

Environment



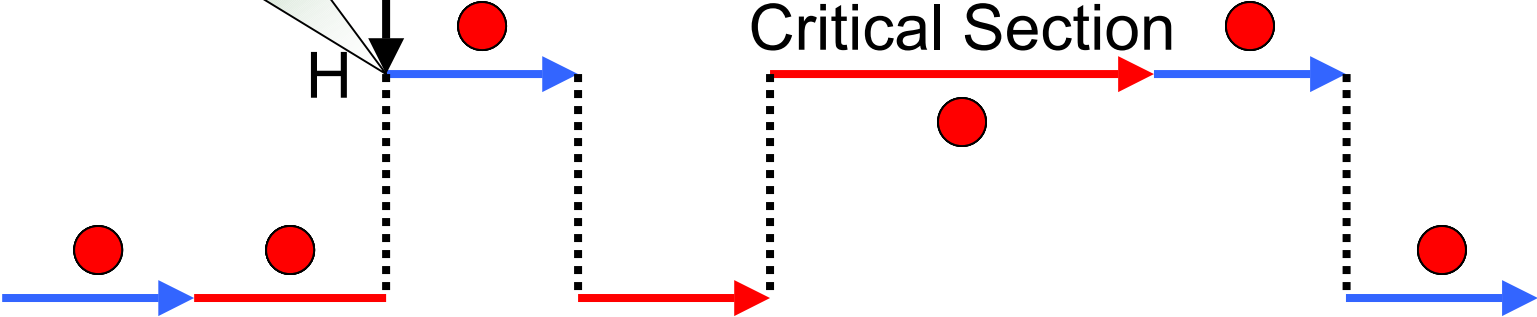
H

Critical Section

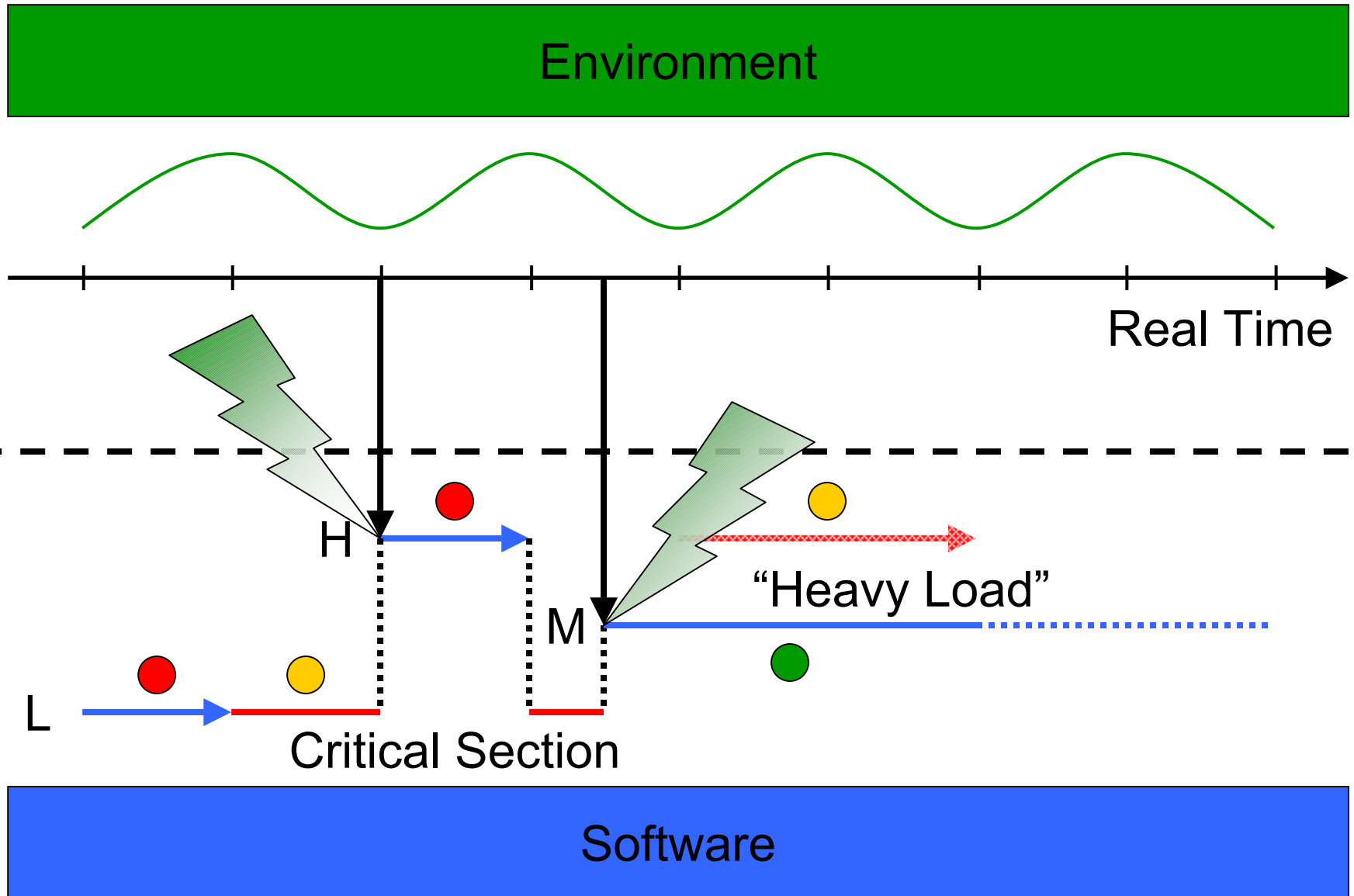
L

Critical Section

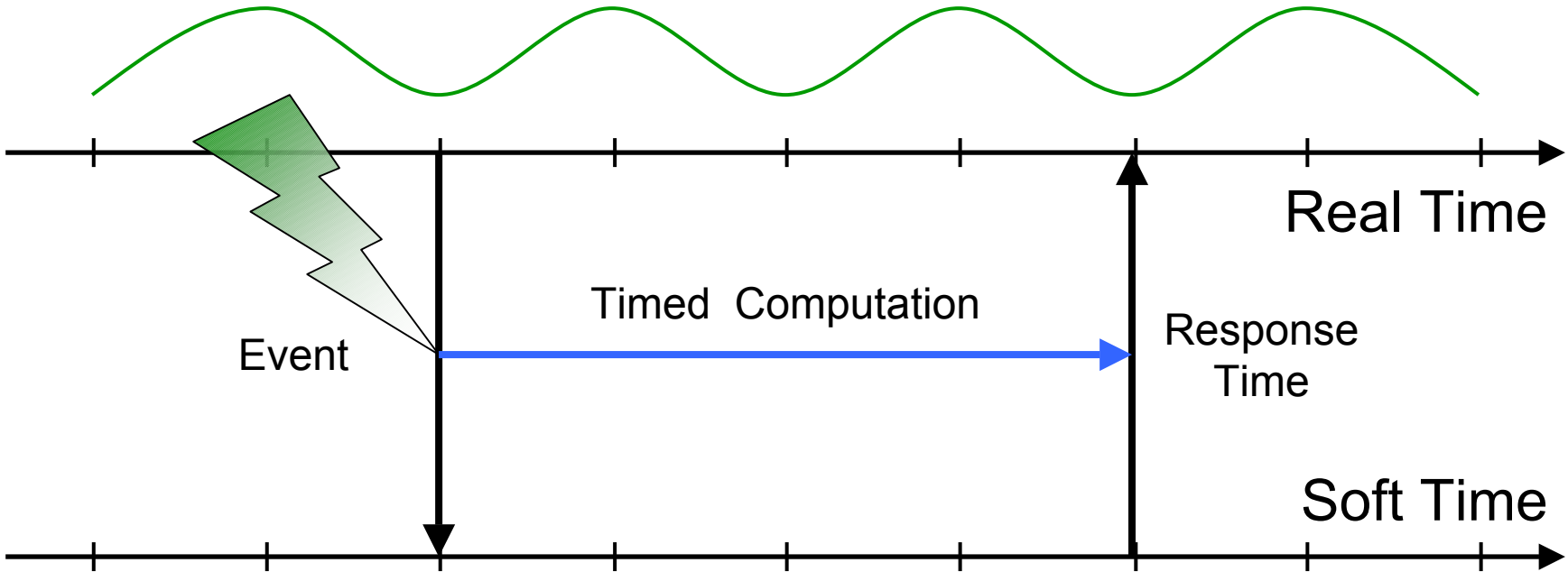
Software



Unbounded Soft Time



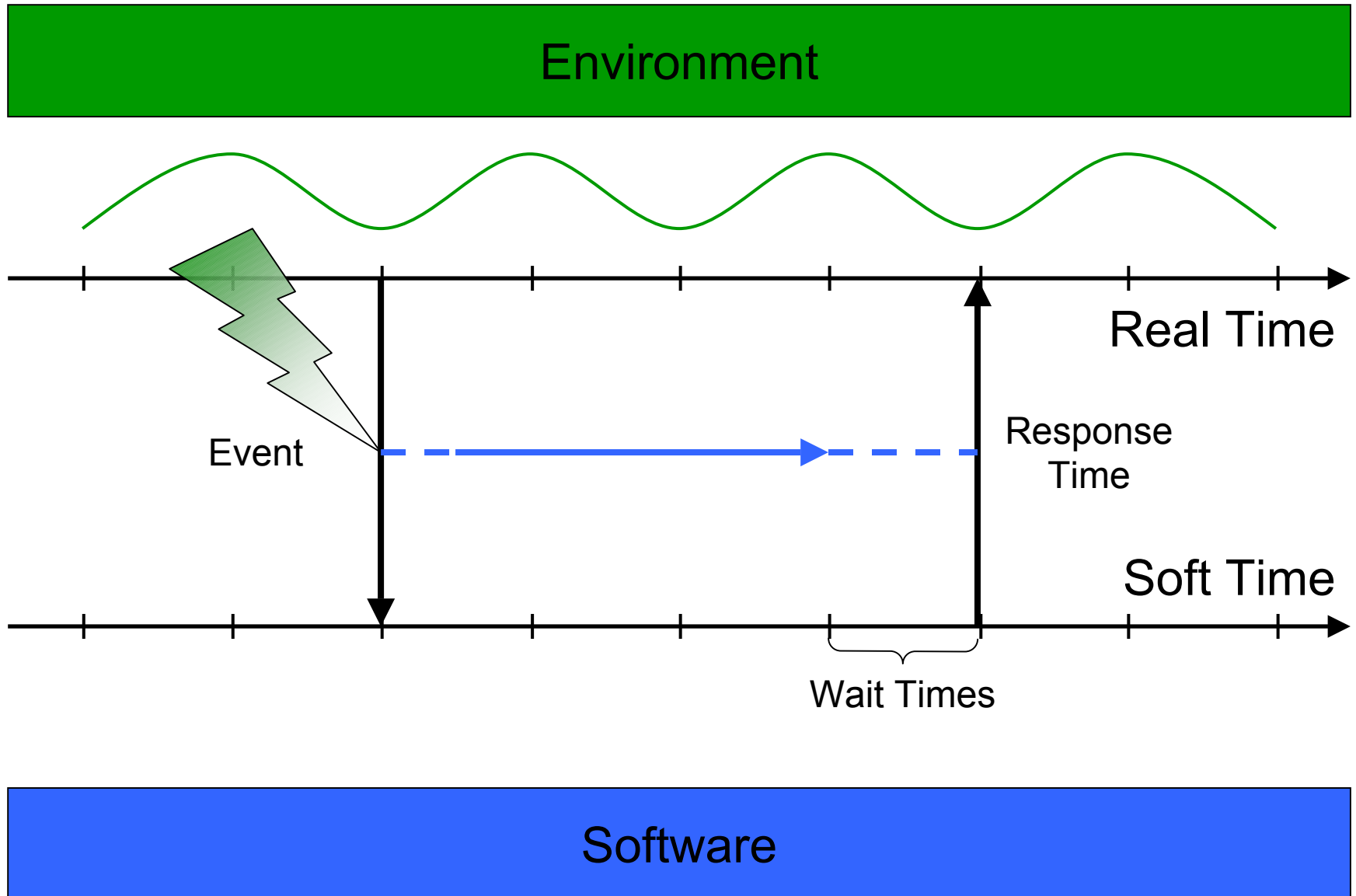
The Timed Model



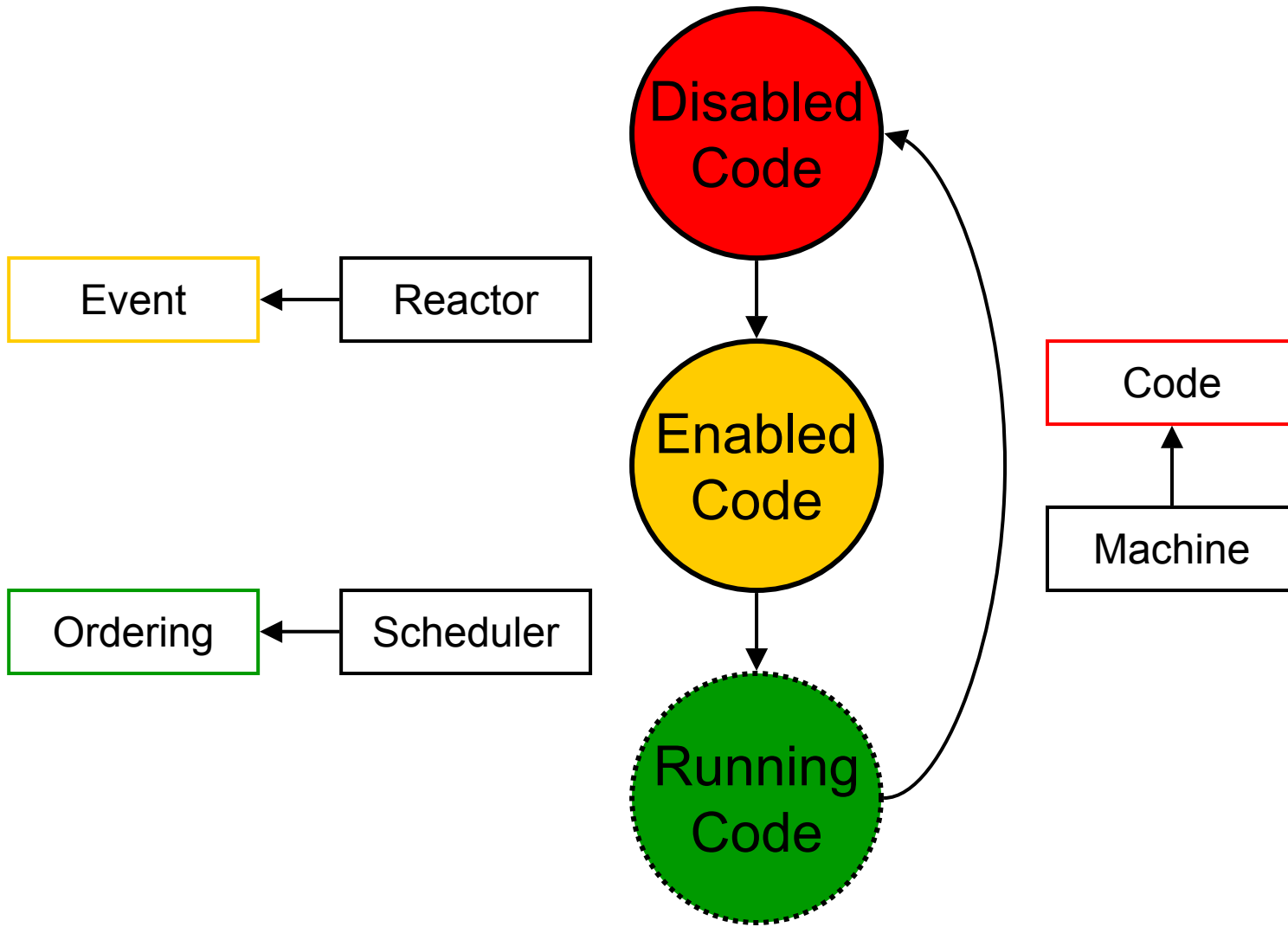
$$\text{Soft-Time} = \text{Real-Time}$$



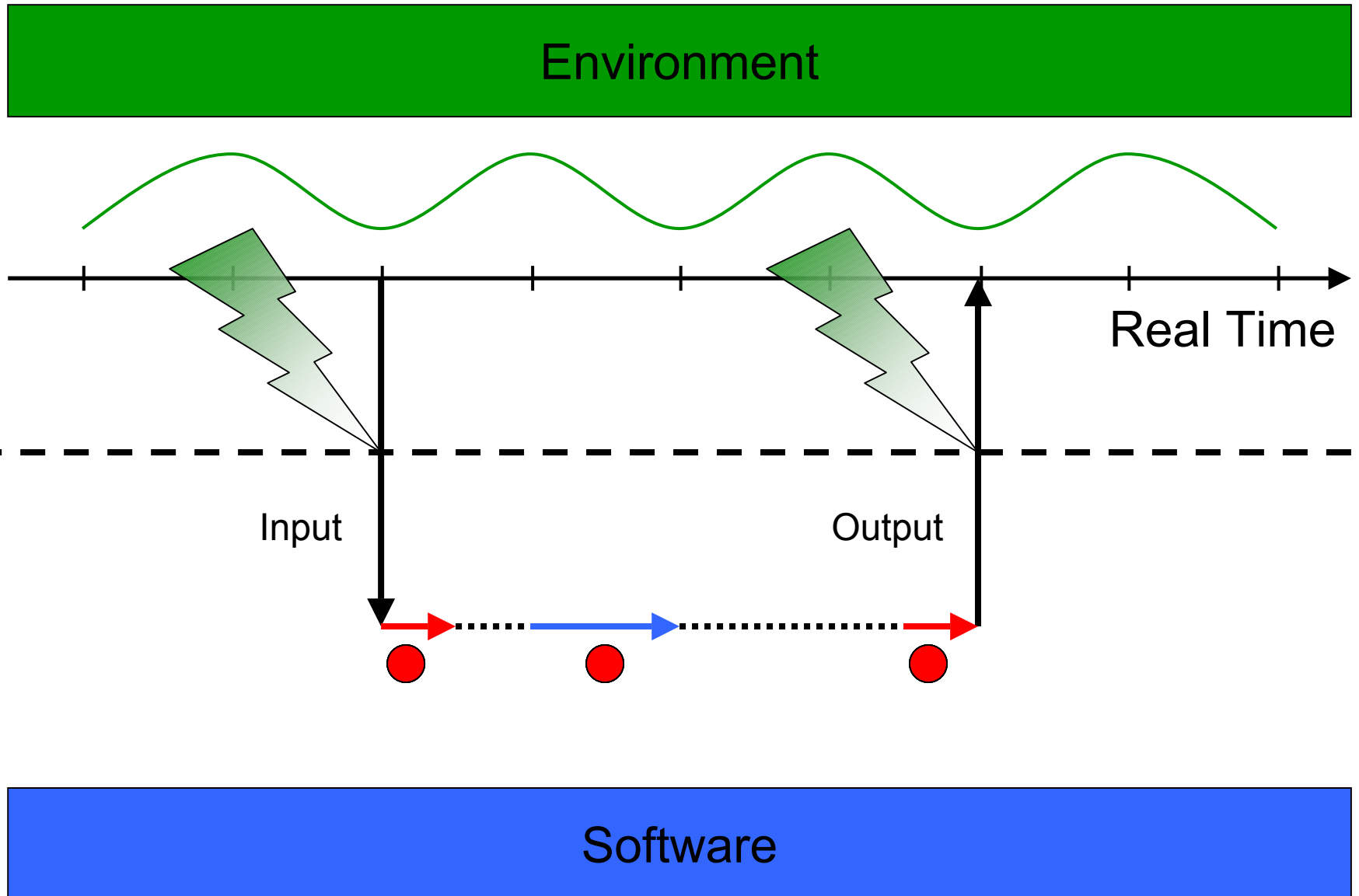
A Timed Implementation



Time Safety



Software vs. Environment Event



E Code

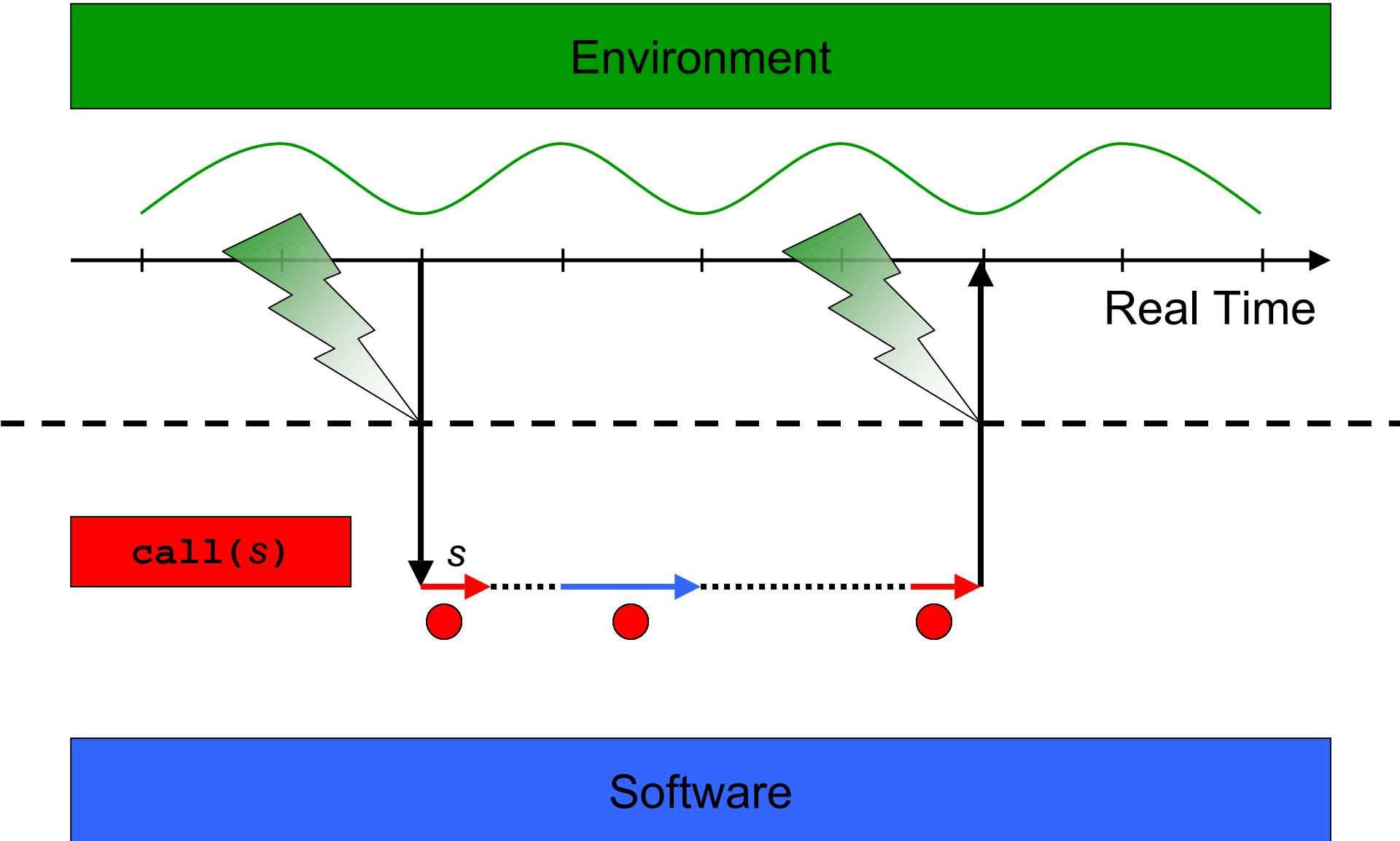
Environment

Real Time

`call(s)`

`s`

Software

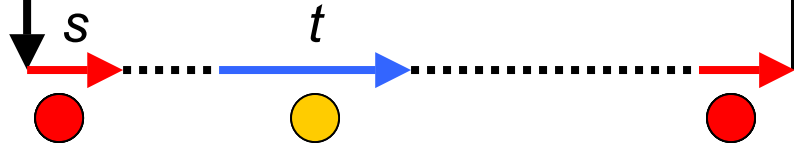


E Code

Environment

Real Time

`call(s)`
`schedule(t)`



Software

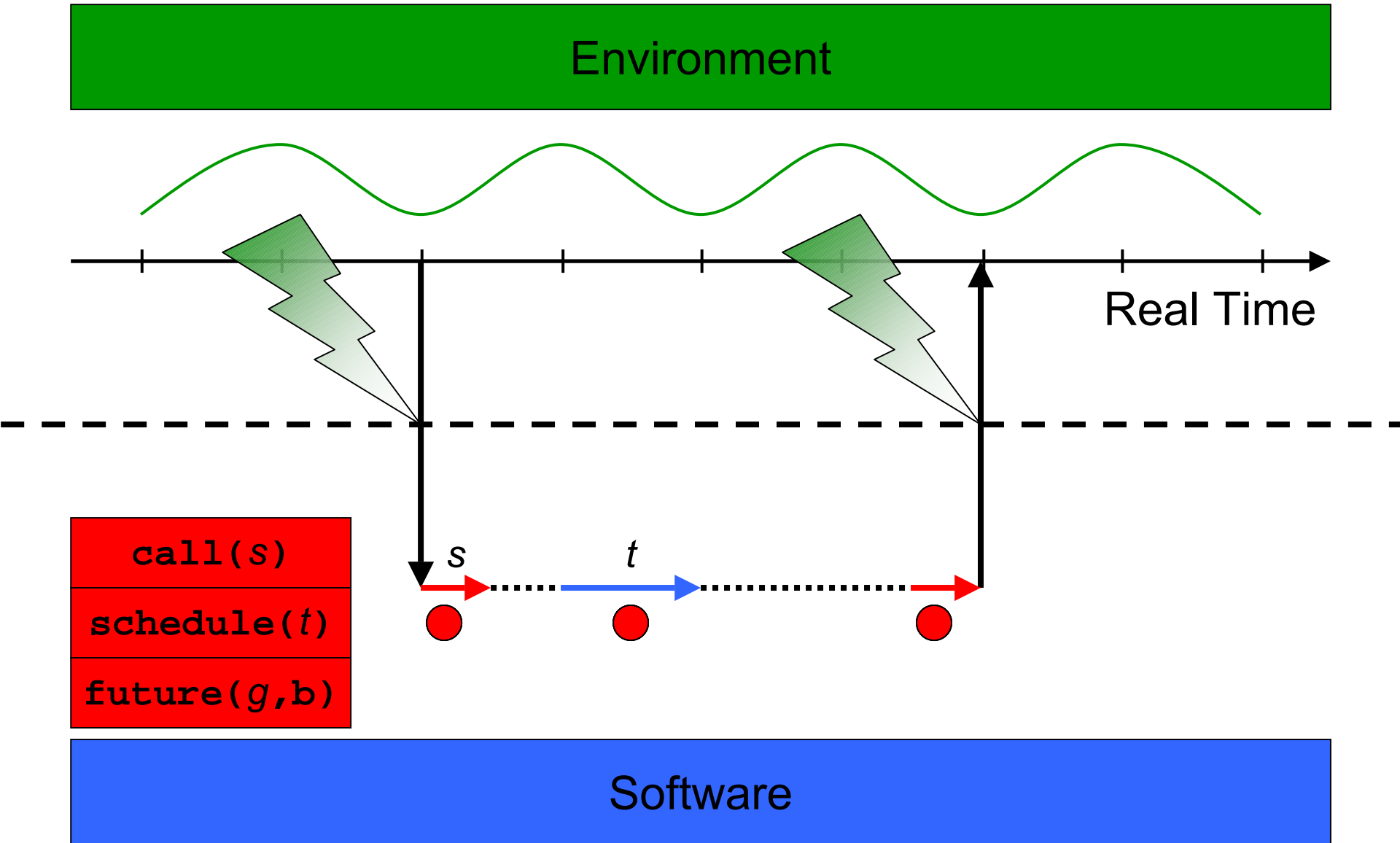
E Code

Environment

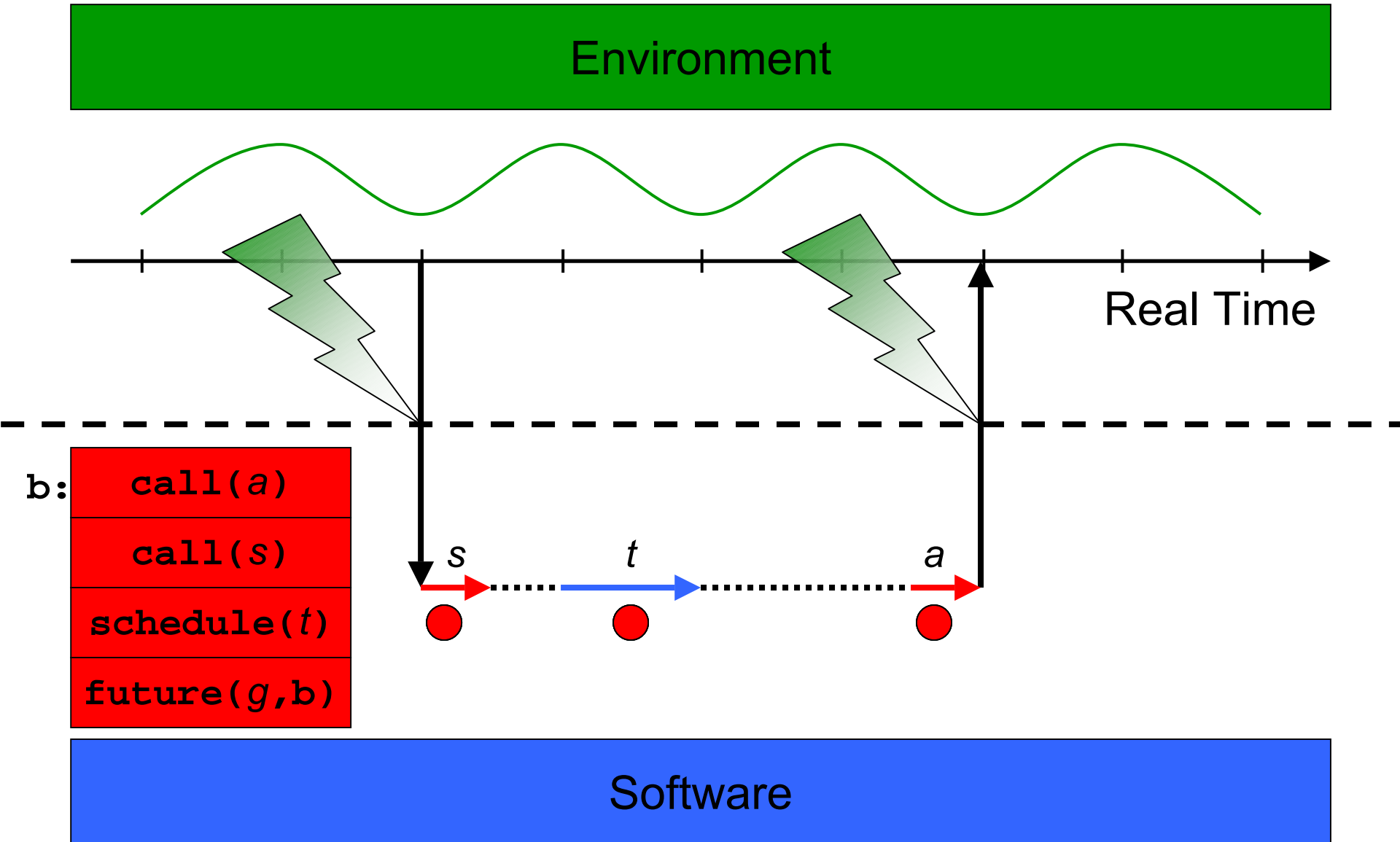
Real Time

| |
|--------------------------|
| <code>call(s)</code> |
| <code>schedule(t)</code> |
| <code>future(g,b)</code> |

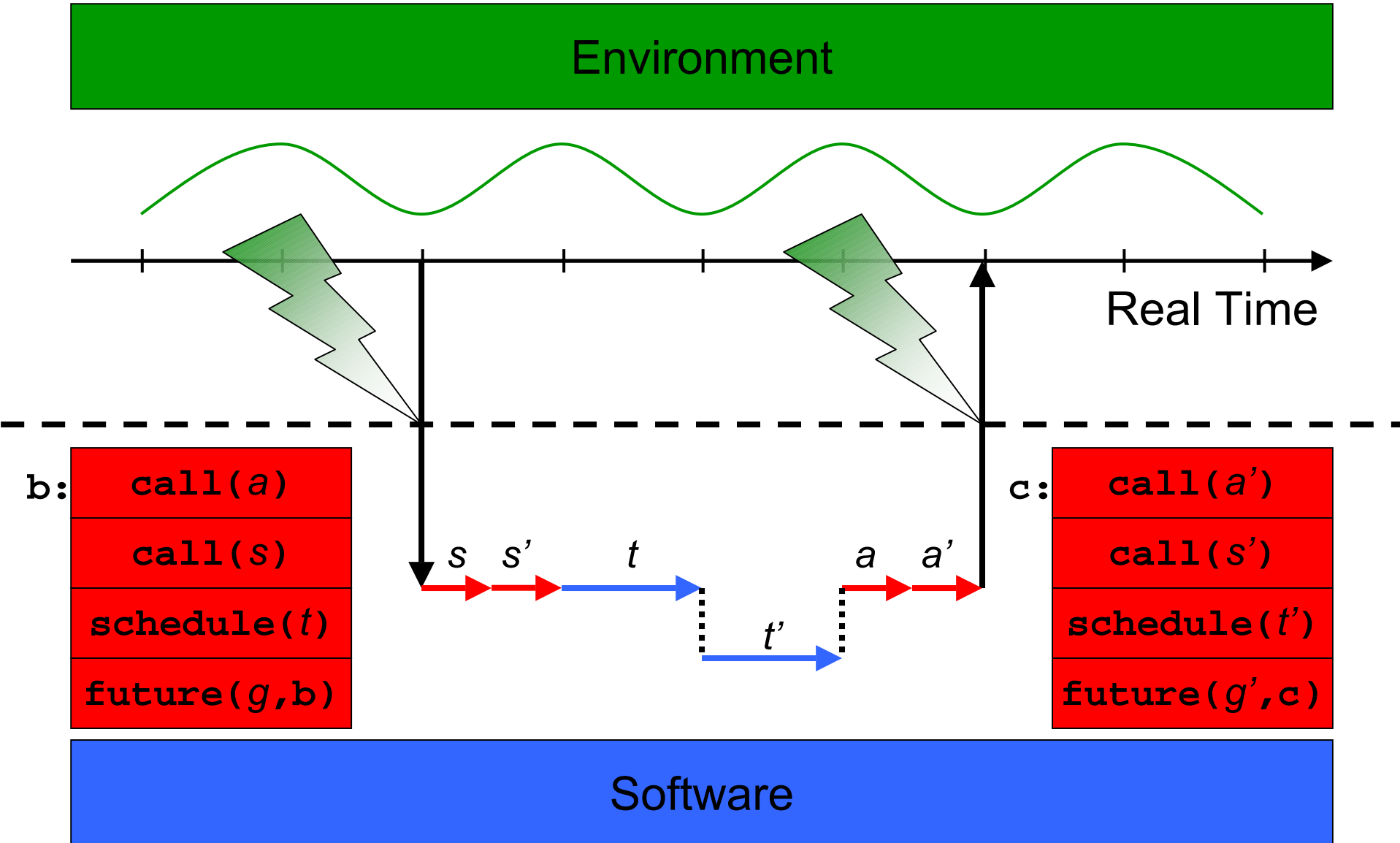
Software



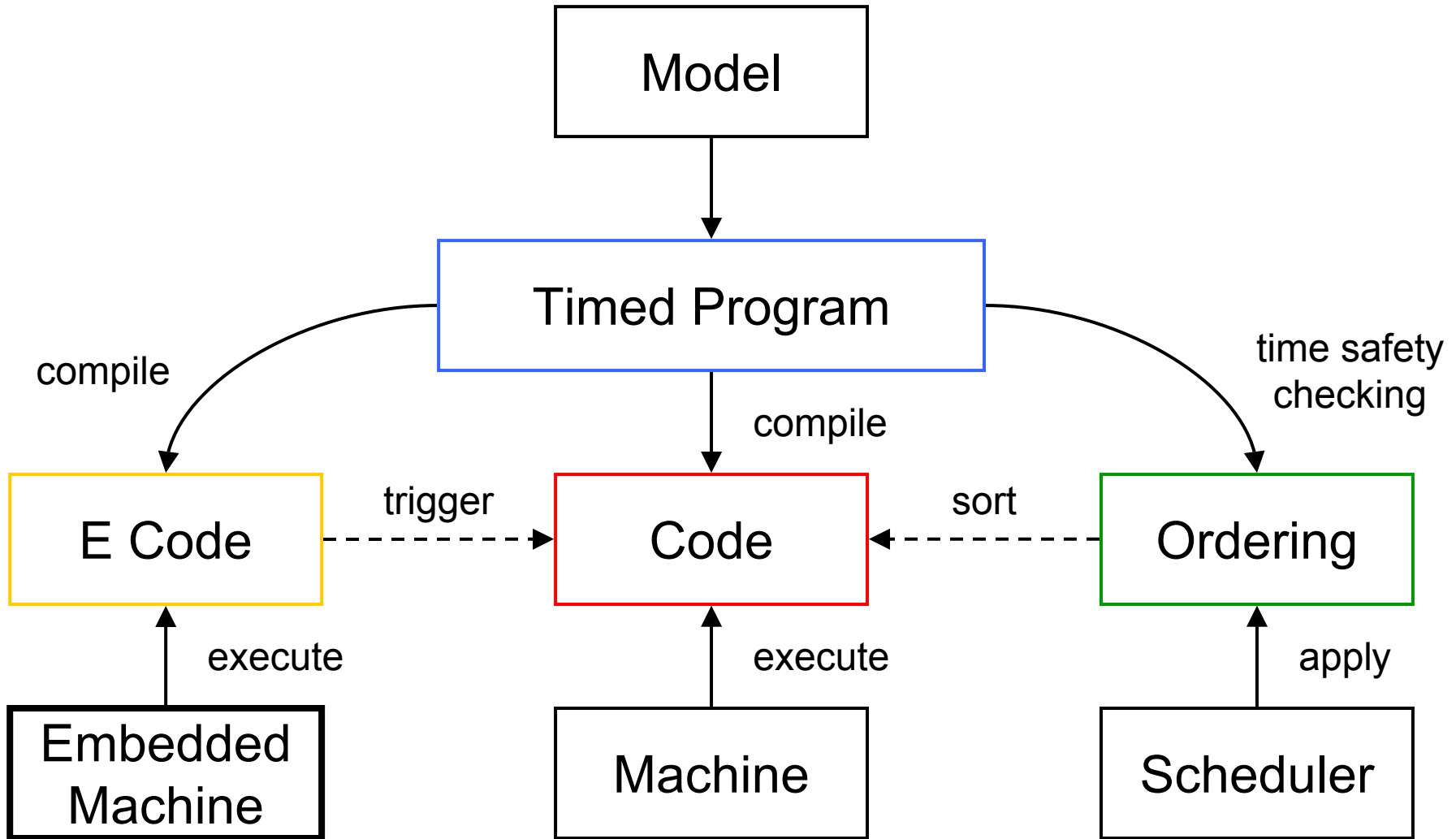
E Code



Composability and Time Safety



The Embedded Machine



Credits

- Synchronous Programming:
 - Esterel
 - Lustre
 - Signal
 - and many more
- Scheduled Programming:
 - Real-Time Operating Systems
 - Real-Time Scheduling Theory
 - Real-Time Communication Protocols
- Classical Compiler Technology:
 - Modular/Incremental Compilation
 - Abstract Machines